integrated detection of angle or speed of rotation (option)

Torque Sensor

CAD data 2D/3D for this sensor:

Rotating, non-contact transmission of measured value, Model 8651

	Ranges 0	± 50 Nm	up to 0	± 1000 Nm
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Code:

Delivery:

Warranty:

- Non-linearity up to 0.1 % F.S.
- Analog output signal ± 10 V Maintenance-free operation
- Angle or speed measurement (option)
- Max. speed 35000 min⁻¹
- Protection class IP67, data sheet on request

Application

The slip-ring-free torque sensor for the measurement of torque, angular rotation or speed with integral measuring amplifier is suitable for use in the laboratory and in an industrial environment.

Thanks to the inductive, non-contact transfer of the excitation voltage and the optical, non-contact transmission of the measuring signal, the sensor can be used wherever low-wear and maintenance-free operation, high speeds or continuous running are required.

The reliable measurement of constant and variable torgues on rotating and standing shaft enables it to be used in guality assurance in the test area and in test rigs and machines as well as in the service area.

Description

The main components of the torque sensor consist of the measuring shaft with applied precision strain gauge, the rotating electronics with secondary coil and optical transmission ring. Power is supplied to the strain gauge bridge without contact by means of a rotary transformer.

A torque applied between the two ends of the shaft produces a mechanical strain, which is measured with the help of a strain gauge bridge circuit. An output signal is obtained from the bridge, which is proportional to the applied torque. This voltage converted into a frequency-modulated signal is transmitted by means of infrared LEDs to the receiver in the stator.

As an option, a conditioned, rectangular output voltage of 5 V can be provided for the direct further processing of the angle or speed of rotation signal by means of the electronics integrated within the sensor.

Use couplings to avoid axial lateral forces and bending moments caused by parallel or angle deviation.





ex stock / 4 weeks

24 months



Table 1

Technical Data					Та	able 1											
Order Code	Measurement Range [Nm]	A1	A2	В	D1g6 ø	D2g6 ø	D3-0,1 ø	Н	H1	L	L1	L2	L3	L4	LK±0.1 ø	M1	M2
8651 - 5050-V0000	0± 50	42	40	56	26	26	54	73	28	170	72	45	45	78	65	deep	deep
8651 - 5100-V0000	0 ± 100	42	40	56	26	26	54	73	28	170	72	45	45	78	65	x8d	4×8d
8651 - 5200-V0000	0± 200	42	40	56	26	26	54	73	28	170	72	45	45	78	65	M4>	M45
8651 - 5500-V0000	0 ± 500 0	46	70	88	45	45	80	104	44	270	84	85	85	90	98	12 deep	12 deep
8651 - 6001-V0000	0 ± 1000,0	46	70	88	45	45	80	104	44	270	84	85	85	90	98	M6x1	M6×1
Higher measurement ranges, up to 20 000 Nm, on request. Dim. tolerance acc. DIN 2768-m																	

Higher measurement ranges, up to 20 000 Nm, on request. Creations based on

Table (

Specifications, bas	sed on measure	ment range	Table 2							
Order Code	Measurement	Spring Con-	Mass Moment of	Max. Permis-	Max. Permissible	Weight	Max. Rotary			
	Range	stant C	Inertia J	sible Axial Load	Radial Load		Speed			
	[Nm]	[Nm/rad]	[g · cm²]	[N]	[N]	[g]	[¹/min]			
8651 - 5050-V0000	0 ± 50	17 x 10 ³	690	1 800	125	1 300	13 000			
8651 - 5100-V0000	0 ± 100	31 x 10 ³	700	1 800	215	1 300	13 000			
8651 - 5200-V0000	0 ± 200	55 x 10 ³	730	1 800	450	1 300	13 000			
8651 - 5500-V0000	0 ± 500	266 x 10 ³	9 400	4 150	650	4 500	7 900			
8651 - 6001-V0000	0 ± 1000	400 x 10 ³	9 600	4 150	1 275	4 500	7 900			

Electrical values

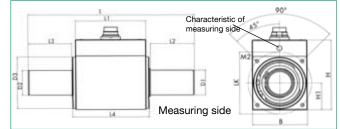
Torque sensor

Excitation voltage U	+ 15 V DC +5 %/-10 %
Excitation current: without option	< 130 mA
with option	< 150 mA
Output at rated capacity:	± 10 V
Tolerance of sensitivity:	0.2 %
Rise time 10 90 %:	2 ms
Internal resistance:	100 Ω
Insulation resistance:	> 5 MΩ
Cut-off frequency - 3dB:	200 Hz
Ripple:	< 100 mV _{ss}
Calibration signal:	the output voltage is +10V,
	if U _k at Pin 6 res. Pin K is put on
The supply is electrically isolated	I from the measuring channel.
Angle and speed sensor (opti-	I from the measuring channel. ons, see table below)
Angle and speed sensor (option Output:	I from the measuring channel. ons, see table below) open coll.
Angle and speed sensor (option Output: Internal pull-up resistor:	I from the measuring channel. ons, see table below) open coll. 10 $k\Omega$ (5 V level)
Angle and speed sensor (option Output: Internal pull-up resistor: External pull-up	I from the measuring channel. ons, see table below) open coll. 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA
Angle and speed sensor (option Output: Internal pull-up resistor:	I from the measuring channel. ons, see table below) 0 open coll. 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA I _{max} = 20 mA)
Angle and speed sensor (opti- Output: Internal pull-up resistor: External pull-up (Current open-collector output: Angle measurement:	I from the measuring channel. ons, see table below) open coll. 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA I _{max} = 20 mA) 360 pulses per round
Angle and speed sensor (opti- Output: Internal pull-up resistor: External pull-up (Current open-collector output: Angle measurement: indicated of direction by two	I from the measuring channel. ons, see table below) 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA I _{max} = 20 mA) 360 pulses per round pulse-outputs, displacement of
Angle and speed sensor (opti- Output: Internal pull-up resistor: External pull-up (Current open-collector output: Angle measurement: indicated of direction by two phase 90° ahead output A, at	I from the measuring channel. ons, see table below) open coll. 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA I _{max} = 20 mA) 360 pulses per round
Angle and speed sensor (opti- Output: Internal pull-up resistor: External pull-up (Current open-collector output: Angle measurement: indicated of direction by two phase 90° ahead output A, at side.	I from the measuring channel. ons, see table below) 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA I _{max} = 20 mA) 360 pulses per round pulse-outputs, displacement of clockwise direction of the driving
Angle and speed sensor (opti- Output: Internal pull-up resistor: External pull-up (Current open-collector output: Angle measurement: indicated of direction by two phase 90° ahead output A, at	I from the measuring channel. ons, see table below) 10 k Ω (5 V level) U _{max} = 24 V / I _{max} = 20 mA I _{max} = 20 mA) 360 pulses per round pulse-outputs, displacement of

opood modelai omond	
Max. speed:	10 000 ¹ /min
Environmental	conditions
Operating temperature	range: 0 °C 60 °C
Temperature compensa	tted: 5 °C 45 °C
Temperature effect:	
on zero	± 0.02 % F.S./K
on span	+ 0.01 % F.S./K
Mechanical val	ues
Non-linearity:	< ± 0.1 % F.S.
Hysteresis:	< ± 0.1 % F.S.
Torque of usage:	200 % of nominal torque
Fracture torque:	300 % of nominal torque
Alternating load:	70 % of nominal torque
Material:	
case	high tensile, anodized aluminium
shafts	stainless construction steel
Protection class acc. E	N 60529: IP40
Mechanical coupling:	round shaft ends
Weight:	see table 2
Electrical connection:	6 pins coupling socket, model 9953
se	nsor without option angle or speed detection
	(included on delivery)
Electrical connection:	12 pins coupling socket model 9940
	sensor with option angle or speed detection

(included on delivery)

Dimensional drawing model 8651



The CAD drawing (3D/2D) for this sensor can be imported online directly into your CAD system.

Download via www.burster.com or directly at www.traceparts.com. For further information about the burster traceparts cooperation refer to data sheet 80-CAD-EN.

Mounting Instructions

Both ends and bottom of sensor case with 4 threaded holes for fixing see drawing and table Installing the sensor, make sure that the shaft ends are aligned as much possible to each other. Avoid damages through radial and angle disalignment by using couplings. For further information refer to the manual. Never exceed the limit of axial and radial forces, shown in table 2.

Order Information

Torque sensor, range 100 Nm	Model 8651-5100-V0000
Accessories For sensor without option speed or Mating connector 6 pin	angle detection Model 9953
Connecting cable, length 3 m, one end free	Model 99553-000C-0160030
For sensor included option speed of	or angle detection
Mating connector 12 pin Connection cable, length 3 m,	Model 9940
one end free	Model 99540-000B-0270030
For sensor included option angle d Mains adapter for standard rail,	etection
15 V DC, ± 5 %, 0,4 A	Model 8651-Z004
Maine adaptor 15 V DC stabilized 1	A Model 4497 V001

Mains adapter 15 V DC, stabilized, 1 A Model 4497-V001

Code	Description
Vxx1x	integral angle detection, 360 pulses per round
Vxx2x	integral speed detection, 60 pulses per round
Vxxx2	shaft end with keyways

Manufacturer Calibration Certificate (WKS)

Calibrated of a sensor or a sensor with indicator for clockwise or counter clockwise torques in 20 % steps raising and decreasing.